

Servomotor – nastavenie

```
#include <Servo.h>
Servo myservo;
void setup()
{
  myservo.attach(9);
}
void loop()
{
  myservo.write(10);
  delay(1000);
  myservo.write(40);
  delay(1000);
  myservo.write(80);
  delay(1000);
  myservo.write(120);
  delay(1000);
  myservo.write(160);
  delay(1000);
}
```

