

Servomotor potenciometer

```
#include <Servo.h>
Servo myservo;
int pos = 0;
void setup()
{
  myservo.attach(9);
}
void loop()
{
  pos = analogRead(A2);
  pos = map(pos, 0, 1023, 0, 179);
  myservo.write(pos);
  delay(5);
}
```

