

Servomotor s dvoma tlačidлами

```
#include <Servo.h>
Servo myservo;
int servoPin = 9;
int leftButton = 2;
int rightButton = 3;
int servoPos = 90;
int delayPeriod = 2;
void setup()
{
  myservo.attach(servoPin);
  myservo.write(servoPos);
  pinMode(leftButton, INPUT);
  pinMode(rightButton, INPUT);
}
void loop()
{
  if(digitalRead(leftButton) == LOW)
  {
    if(servoPos > 0)
    {
      servoPos--;
    }
    myservo.write(servoPos);
    delay(delayPeriod);
  }
  if(digitalRead(rightButton) == LOW)
  {
    if(servoPos < 180)
    {
      servoPos++;
    }
    myservo.write(servoPos);
    delay(delayPeriod);
  }
}
```

